

NAME

own, **own_send_command**, **own_command_wait**, **own_self_command**, **own_acquire_bus**, **own_crc**,
own_release_bus, **OWN_ACQUIRE_BUS**, **OWN_CRC**, **OWN_RELEASE_BUS**,
OWN_SEND_COMMAND - Dallas Semiconductor 1-Wire Network and Transport Interface

SYNOPSIS

```
#include <sys/bus.h>
```

```
#include <dev/ow/own.h>
```

int

```
own_send_command(device_t pdev, struct ow_cmd *cmd);
```

int

```
own_command_wait(device_t pdev, struct ow_cmd *cmd);
```

int

```
own_self_command(device_t pdev, struct ow_cmd *cmd, uint8_t xpt_cmd);
```

int

```
own_acquire_bus(device_t pdev, int how);
```

int

```
own_release_bus(device_t pdev);
```

int

```
own_crc(device_t pdev, uint8_t *buffer, size_t len);
```

int

```
OWN_SEND_COMMAND(device_t ndev, device_t pdev, struct ow_cmd *cmd);
```

int

```
OWN_ACQUIRE_BUS(device_t ndev, device_t pdev, int how);
```

void

```
OWN_RELEASE_BUS(device_t ndev, device_t pdev);
```

uint8_t

```
OWN_CRC(device_t ndev, device_t pdev, uint8_t *buffer, size_t len);
```

DESCRIPTION

The **own** interface defines three sets of functions for interacting with 1-Wire devices: sending commands, reserving the bus, and ensuring data integrity. Wrappers are provided for the raw **OWN** kobj(9) interfaces and should be used for improved safety over the kobj(9) ones.

Bus Commands

The 1-Wire bus defines different layers of access to the devices on the bus. The **own** functions provide access to the network and transport layers. The network layer designates the next command as being either for all devices on the bus, or for a specific device. The network layer also specifies the speed used by the link layer.

struct ow_cmd encapsulates network access, speed, and timing information. It specifies the commands to send and whether or not to read data. Its members are:

flags Flags controlling the interpretation of the structure. These flags are defined in *<dev/ow/ow.h>*:

OW_FLAG_OVERDRIVE

Send *xpt_cmd* bytes and read *xpt_read* bytes at overdrive speed.

OW_FLAG_READ_BIT

Interpret *xpt_read_len* to be in bits to be read after *xpt_cmd* rather than bytes.

rom_cmd

ROM command bytes to send.

rom_len

Number of ROM command bytes to send.

rom_read_len

Number of bytes to read after sending the ROM command.

rom_read

Buffer for bytes read after the ROM command.

xpt_cmd

Transport command to send.

xpt_len

Length of the transport command bytes to send. Specify 0 for no transport command.

xpt_read_len

Number of bytes to read after *xpt_cmd* bytes are sent. If the `OW_FLAG_READ_BIT` bit is set in *flags*, then it is the number of bits to read. Bits read are packed into bytes.

xpt_read

Buffer for data read.

own_command_wait() acquires the 1-Wire bus, waiting if necessary, sends the command, and then releases the bus. **own_send_command()** sends the command without bus reservation. *pdev* is the client device (the presentation layer device) sending the command. The *cmd* argument describes the transaction to send to the 1-Wire bus.

own_self_command() fills in *cmd* with a `MATCH_ROM` command, the ROM address of *pdev* and the *xpt_cmd* as a convenient way to create directed commands.

Bus Reservation

The 1-Wire system includes an advisory lock for the bus that presentation layer devices can use to coordinate access. Locking is purely advisory at this time.

own_acquire_bus() reserves the bus. It waits indefinitely if the *how* argument is `OWN_WAIT` and returns the error `EWOULDBLOCK` if passed `OWN_DONTWAIT` when the bus is owned by another client.

own_release_bus() releases the bus.

Data Integrity

own_crc() computes the 1-Wire standard CRC function over the data passed in *buffer* and *len* and returns the result.

Notes

The 1-Wire standard (Maxim AN937) defines layers that are akin to ISO networking layers. The lowest relevant layer, the link layer, defines the polling windows and the timing of the signaling of different modes. The network layer is built on top of the link layer and is used to address devices in a unicast or multicast manner. The transport layer defines commands and responses from the devices. The presentation layer is composed of the device specific commands and actions used to control the specific 1-Wire devices on bus.

These interfaces are implemented by the `ow(4)` device. Presentation layer devices (children of the newbus `ow(4)` device) should only call the functions described here. The functionality provided by the `owc(4)` device (specifically the `owll(9)` interface) should only be called by the `ow(4)` driver.

SEE ALSO

ow(4), owc(4), owl(9) *<https://pdfserv.maximintegrated.com/en/an/AN937.pdf>*

LEGAL

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HISTORY

The **own** driver first appeared in FreeBSD 11.0.

AUTHORS

The **own** device driver and this manual page were written by Warner Losh.