

NAME

smb - SMB generic I/O device driver

SYNOPSIS

device smb

DESCRIPTION

The *smb* character device driver provides generic I/O to any *smbus(4)* instance. To control SMB devices, use */dev/smb?* with the *ioctl*s described below. Any of these *ioctl* commands takes a pointer to *struct smbcmd* as its argument.

```
#include <sys/types.h>
```

```
struct smbcmd {
    u_char cmd;
    u_char reserved;
    u_short op;
    union {
        char  byte;
        char  buf[2];
        short word;
    } wdata;
    union {
        char  byte;
        char  buf[2];
        short word;
    } rdata;
    int slave;
    char *wbuf; /* use wdata if NULL */
    int wcount;
    char *rbuf; /* use rdata if NULL */
    int rcount;
};
```

The *slave* field is always used, and provides the address of the SMBus slave device. The slave address is specified in the seven most significant bits (i.e., "left-justified"). The least significant bit of the slave address must be zero.

<i>Ioctl</i>	<i>Description</i>
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SMB_QUICK_WRITE	<i>QuickWrite</i> does not transfer any data. It just issues the device address with write intent to the bus.
SMB_QUICK_READ	<i>QuickRead</i> does not transfer any data. It just issues the device address with read intent to the bus.
SMB_SENDB	<i>SendByte</i> sends the byte provided in <i>cmd</i> to the device.
SMB_RECVB	<i>ReceiveByte</i> reads a single byte from the device which is returned in <i>cmd</i> .
SMB_WRITEB	<i>WriteByte</i> first sends the byte from <i>cmd</i> to the device, followed by the byte given in <i>wdata.byte</i> .
SMB_WRITEW	<i>WriteWord</i> first sends the byte from <i>cmd</i> to the device, followed by the word given in <i>wdata.word</i> . Note that the SMBus byte-order is little-endian by definition.
SMB_READB	<i>ReadByte</i> first sends the byte from <i>cmd</i> to the device, then reads one byte of data from the device. Returned data is stored in <i>rdata.byte</i> .
SMB_READW	<i>ReadWord</i> first sends the byte from <i>cmd</i> to the device, then reads one word of data from the device. Returned data is stored in <i>rdata.word</i> .
SMB_PCALL	<i>ProcedureCall</i> first sends the byte from <i>cmd</i> to the device, followed by the word provided in <i>wdata.word</i> . It then reads one word of data from the device and returns it in <i>rdata.word</i> .
SMB_BWRITE	<i>BlockWrite</i> first sends the byte from <i>cmd</i> to the device, then the byte from <i>wcount</i> followed by <i>wcount</i> bytes of data that are taken from the buffer pointed to by <i>wbuf</i> . The SMBus specification mandates that no more than 32 bytes of data can be transferred in a single block read or write command. This value can be read from the constant <code>SMB_MAXBLOCKSIZE</code> .
SMB_BREAD	<i>BlockRead</i> first sends the byte from <i>cmd</i> to the device, then reads a count of data bytes that the device is going to provide and then reads that many bytes. The count is returned in <i>rcount</i> . The data is returned in the buffer pointed to by <i>rbuf</i> .

The `read(2)` and `write(2)` system calls are not implemented by this driver.

ERRORS

The `ioctl(2)` commands can cause the following driver-specific errors:

[ENXIO]	Device did not respond to selection.
[EBUSY]	Device still in use.
[ENODEV]	Operation not supported by device (not supposed to happen).

[EINVAL] General argument error.

[EWOULDBLOCK] SMBus transaction timed out.

SEE ALSO

ioctl(2), smb(4)

HISTORY

The **smb** manual page first appeared in FreeBSD 3.0.

AUTHORS

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